

C-Ludics and Natural Language

Christophe Fouqueré

Laboratoire d'Informatique de Paris-Nord
Université de Paris 13 - CNRS 7030

- 1 C-Designs
- 2 Automata and Generators
- 3 Natural Language

Computational Ludics (K. Terui, 2008)

- **Goal:** Logical reconstruction of computability and complexity theory
- **Why** based on Ludics: monism, interaction, existentialism
 - **Monism:** One kind of object versus automata/word, program/data, grammar/sentence, . . .
 - **Interaction:**
 - Primitive of computation (cf Curry-Howard), acceptance viewed as orthogonality
 - Symmetry of the process (versus functions)
 - **Existentialism:** not necessarily closed objects

Computational Ludics: Preliminary Results

- Correspondence with *automata theory*
- Computational presentation of (generalized) Ludics (and generalization of completeness properties)
- Introduction of *design generators* (hence finite presentation of infinite designs)

Ludics vs Automata

Correspondence:

set of Actions	vs	Alphabet
Design	vs	Word
Behaviour	vs	Language
Formula/Type	vs	(eg reg.) Expression

Orthogonality vs **Acceptance**

$\mathcal{D} \perp \mathcal{R}$ iff $\llbracket \mathcal{D}, \mathcal{R} \rrbracket = \mathcal{D} \text{ ai}$ iff \mathcal{D}^* is accepted by \mathcal{R}^*

Generalizing Ludics (1)

First of all, Terui defines:

- A **term language** for design presentation.
- A specific language for **generating** designs, hence giving the possibility to speak of, say, regular expressions.

Generalizing Ludics (2)

Second:

- Loci addresses are absolute and reflect a chronicle order
➔ In an action, a focus and its ramification are replaced by a **name** together with a set of (distinct) **variables**. Hence, variables may be replaced/reduced by designs during a normalization step.

Generalizing Ludics (3)

Third:

- Designs are cut-free, however a design may be the normalized form between two designs
 - ➔ Explicit **cuts** are added to the term language.

- Designs are identity-free
 - ➔ As soon as variables are part of the term language, replacing a variable by another one is nothing else but an **identity**.

Term Language

- Girard/Curien's original designs:
 - Normal, η -expanded, linear lambda terms (maybe infinitary).
 - Actions built with ramifications: $I \in \mathcal{P}_f(\mathbb{N})$.
 - (in Desseins) a node is addressed by a locus.
 - (in Desseins) children of negative nodes may have a (maybe infinite) set of negative actions with same focus
- **C-designs:**
 - Arbitrary terms.
 - Actions built from a given signature: $\mathcal{A} = (A, ar)$ where
 - A is a set of names,
 - $ar : A \rightarrow \mathbb{N}$ gives an arity to each name.
 - A term is referenced by a name.
 - A specific constant corresponds to undefined positive subnodes, hence divergence: Ω

Term Language: Actions

Actions are polarized:

- A **positive** action is one of the following:

\boxtimes daemon

Ω divergence

\bar{u} proper positive action, $u \in A$

- A **negative** action is one of the following:

x variable

$u(x_1, \dots, x_{ar(u)})$ proper negative action

(x_1, \dots, x_n noted \vec{x}_i)

Term Language: C-designs

The sets of positive and negative designs are coinductively defined by:

$$\begin{array}{l}
 P ::= \text{\textcircled{X}} \quad \text{daemon} \\
 \quad | \quad \Omega \quad \text{divergence} \\
 \quad | \quad N_0 | \bar{u} \langle \vec{N}_i \rangle \quad \text{proper action} \\
 \\
 N ::= x \quad \text{variable} \\
 \quad | \quad \sum_u u(\vec{x}_i).P_u \quad \text{(negative) choices}
 \end{array}$$

In Ludics:

$$\frac{\frac{\xi 00 \vdash \xi 1 \quad \frac{\overline{\vdash \xi 011} \star}{\xi 01 \vdash}}{\vdash \xi 0, \xi 1} \quad \frac{\xi 10 \vdash \xi 2}{\vdash \xi 1, \xi 2}}{\xi \vdash}$$

or

$$\begin{array}{c} \star \\ | \\ (-, \xi 01, \{1\}) \\ / \quad \backslash \\ (+, \xi 0, \{0, 1\}) \quad (+, \xi 1, \{0\}) \\ \backslash \quad / \\ (-, \xi, \{0, 1\}) \quad (-, \xi, \{1, 2\}) \end{array}$$

As a c-design:

$$\begin{array}{c} \star \\ | \\ C = c(z_1). \star \\ / \quad \backslash \\ B = x_1 \mid \bar{b} \langle \sum u(\vec{x}_i) . \Omega, C + \sum_{u \neq c} u(\vec{x}_i) . \Omega \rangle \quad B' = x'_1 \mid \bar{b}' \langle \sum u(\vec{x}_i) . \Omega \rangle \\ \backslash \quad / \\ a(x_1, x_2) . B + a'(x'_1, x'_2) . B' \end{array}$$

or

$$\begin{aligned} & a(x_1, x_2) . (x_1 \mid \bar{b} \langle \sum u(\vec{x}_i) . \Omega, c(z_1). \star + \sum_{u \neq c} u(\vec{x}_i) . \Omega \rangle) \\ & + a'(x'_1, x'_2) . (x'_1 \mid \bar{b}' \langle \sum u(\vec{x}_i) . \Omega \rangle) \\ & + \sum_{u \neq a, a'} u(\vec{x}_i) . \Omega \end{aligned}$$

Term Normalisation: Extension of λ -calculus

In λ -calculus:

$$(\lambda x_1 \dots x_n. P) N_1 \dots N_n \longrightarrow P[N_1/x_1, \dots, N_n/x_n]$$

In C-Ludics:

- **Reduction rule** of c-designs:

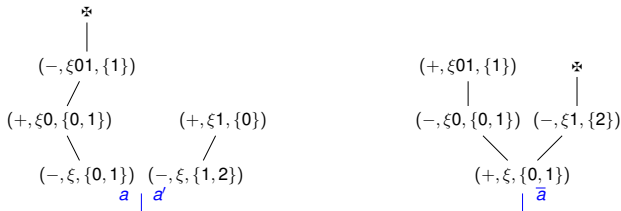
$$\begin{aligned} \sum_u u(x_1 \dots x_{ar(u)}. P_u \mid \overline{u_0} \langle N_1 \dots N_{ar(u_0)} \rangle) \\ \longrightarrow P_{u_0}[N_1/x_1, \dots, N_{ar(u_0)}/x_{ar(u_0)}] \end{aligned}$$

- **Normalization:**

$P \Downarrow Q$ if $P \longrightarrow^* Q$ and Q is neither a cut nor Ω
If such a Q exists, it is noted $\llbracket P \rrbracket$

- **Orthogonality:** $N \perp P$ if $P[N/x] \Downarrow \nexists$

Term Normalization: a Linear Example



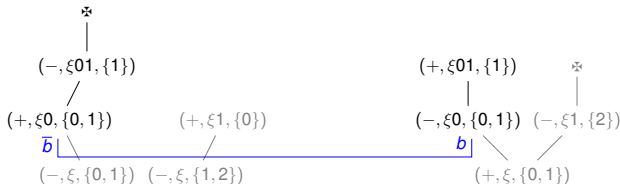
$$\left(a(x_1, x_2). \left(x_1 \mid \bar{b}(\sum u(\vec{x}_i).\Omega), c(z_1).* + \sum_{u \neq c} u(\vec{x}_i).\Omega) \right) + a'(x'_1, x'_2). \left(x'_1 \mid \bar{b}(\sum u(\vec{x}_i).\Omega) \right) + \dots \right) \mid \bar{a}(b(y_1, y_2). (y_2 \mid \bar{c}(\sum u(\vec{x}_i).\Omega)) + \sum_{u \neq b} u(\vec{x}_i).\Omega), b''(y''_1).* + \sum_{u \neq b''} u(\vec{x}_i).\Omega)$$

$$\rightarrow \left(b(y_1, y_2). (y_2 \mid \bar{c}(\sum u(\vec{x}_i).\Omega)) + \sum_{u \neq b} u(\vec{x}_i).\Omega \right) \mid \bar{b}(\sum u(\vec{x}_i).\Omega), c(z_1).* + \sum_{u \neq c} u(\vec{x}_i).\Omega)$$

$$\rightarrow \left(c(z_1).* + \sum_{u \neq c} u(\vec{x}_i).\Omega \right) \mid \bar{c}(\sum u(\vec{x}_i).\Omega)$$

$$\rightarrow *$$

Term Normalization: a Linear Example



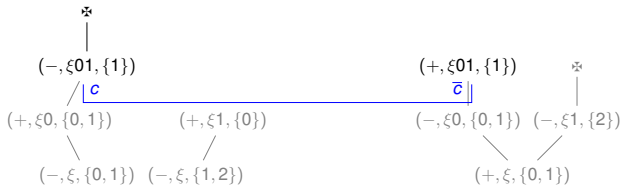
$$\left(a(x_1, x_2). \left(x_1 \mid \bar{b} \langle \sum u(\vec{x}_i).\Omega \rangle, c(z_1). * + \sum_{u \neq c} u(\vec{x}_i).\Omega \right) + a'(x'_1, x'_2). \left(x'_1 \mid \bar{b}' \langle \sum u(\vec{x}_i).\Omega \rangle \right) + \dots \right) \mid \bar{a} \langle b(y_1, y_2). (y_2 \mid \bar{c} \langle \sum u(\vec{x}_i).\Omega \rangle + \sum_{u \neq b} u(\vec{x}_i).\Omega), b''(y''_1). * + \sum_{u \neq b''} u(\vec{x}_i).\Omega) \rangle$$

$$\rightarrow \left(b(y_1, y_2). (y_2 \mid \bar{c} \langle \sum u(\vec{x}_i).\Omega \rangle + \sum_{u \neq b} u(\vec{x}_i).\Omega) \mid \bar{b} \langle \sum u(\vec{x}_i).\Omega \rangle, c(z_1). * + \sum_{u \neq c} u(\vec{x}_i).\Omega \right)$$

$$\rightarrow \left(c(z_1). * + \sum_{u \neq c} u(\vec{x}_i).\Omega \right) \mid \bar{c} \langle \sum u(\vec{x}_i).\Omega \rangle$$

$\rightarrow *$

Term Normalization: a Linear Example



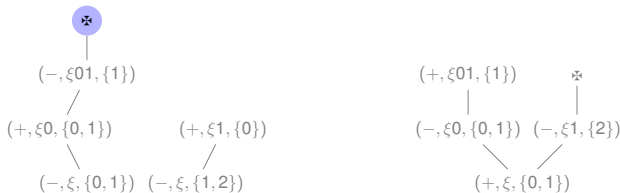
$$\left(a(x_1, x_2). \left(x_1 \mid \bar{b}(\sum u(\vec{x}_i).\Omega), c(z_1).\star + \sum_{u \neq c} u(\vec{x}_i).\Omega) \right) + a'(x'_1, x'_2). \left(x'_1 \mid \bar{b}'(\sum u(\vec{x}_i).\Omega) \right) + \dots \right) \\ \mid \bar{a}(b(y_1, y_2). (y_2 \mid \bar{c}(\sum u(\vec{x}_i).\Omega) + \sum_{u \neq b} u(\vec{x}_i).\Omega), b''(y''_1). \star + \sum_{u \neq b''} u(\vec{x}_i).\Omega))$$

$$\rightarrow \left(b(y_1, y_2). (y_2 \mid \bar{c}(\sum u(\vec{x}_i).\Omega) + \sum_{u \neq b} u(\vec{x}_i).\Omega) \mid \bar{b}(\sum u(\vec{x}_i).\Omega), c(z_1). \star + \sum_{u \neq c} u(\vec{x}_i).\Omega) \right)$$

$$\rightarrow \left(c(z_1). \star + \sum_{u \neq c} u(\vec{x}_i).\Omega \mid \bar{c}(\sum u(\vec{x}_i).\Omega) \right)$$

$\rightarrow \star$

Term Normalization: a Linear Example



$$\left(a(x_1, x_2). \left(x_1 \mid \bar{b} \langle \sum u(\vec{x}_i).\Omega \rangle, c(z_1). \star + \sum_{u \neq c} u(\vec{x}_i).\Omega \right) + a'(x'_1, x'_2). \left(x'_1 \mid \bar{b}' \langle \sum u(\vec{x}_i).\Omega \rangle + \dots \right) \right. \\ \left. \mid \bar{a} \langle b(y_1, y_2). (y_2 \mid \bar{c} \langle \sum u(\vec{x}_i).\Omega \rangle) + \sum_{u \neq b} u(\vec{x}_i).\Omega \rangle, b''(y''_1). \star + \sum_{u \neq b''} u(\vec{x}_i).\Omega \right)$$

$$\rightarrow \left(b(y_1, y_2). (y_2 \mid \bar{c} \langle \sum u(\vec{x}_i).\Omega \rangle) + \sum_{u \neq b} u(\vec{x}_i).\Omega \right) \mid \bar{b} \langle \sum u(\vec{x}_i).\Omega \rangle, c(z_1). \star + \sum_{u \neq c} u(\vec{x}_i).\Omega$$

$$\rightarrow \left(c(z_1). \star + \sum_{u \neq c} u(\vec{x}_i).\Omega \right) \mid \bar{c} \langle \sum u(\vec{x}_i).\Omega \rangle$$

$$\rightarrow \star$$

Term Normalization in the Large

In the previous example:

- Variables are used linearly.
- They specify an immediate sub-cut.

The framework of c-ludics is more general:

- Variables may appear several times.
- Cuts may be put for later usage.

As in the following example...

Term Normalization: a Non-linear Example

$$\begin{aligned}
 & \left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c}(\cdot))) \\
 \rightarrow & (b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \\
 \rightarrow & c(). \left((b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c}(\cdot) \\
 \rightarrow & b(y). (y \mid \bar{c}(\cdot)) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \\
 \rightarrow & (c(). * + \sum_{u \neq c} u(\vec{x}_i). \Omega) \mid \bar{c}(\cdot) \\
 \rightarrow & *
 \end{aligned}$$

Term Normalization: a Non-linear Example

$$\begin{aligned}
 & \left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c}(\cdot))) \\
 \rightarrow & \quad (b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \\
 \rightarrow & \quad c(). \left((b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c}(\cdot) \\
 \rightarrow & \quad b(y). (y \mid \bar{c}(\cdot)) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \\
 \rightarrow & \quad (c(). * + \sum_{u \neq c} u(\vec{x}_i). \Omega) \mid \bar{c}(\cdot) \\
 \rightarrow & \quad *
 \end{aligned}$$

Term Normalization: a Non-linear Example

$$\begin{aligned}
 & \left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c}(\langle \rangle))) \\
 \rightarrow & \left(b(y). (y \mid \bar{c}(\langle \rangle)) \right) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c}(\langle \rangle))) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \\
 \rightarrow & c(). \left((b(y). (y \mid \bar{c}(\langle \rangle)) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega) \right) \mid \bar{c}(\langle \rangle) \\
 \rightarrow & b(y). (y \mid \bar{c}(\langle \rangle)) \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \\
 \rightarrow & \left(c(). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c}(\langle \rangle) \\
 \rightarrow & *
 \end{aligned}$$

Term Normalization: a Non-linear Example

$$\begin{aligned}
 & \left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c} \langle \rangle)) \\
 \rightarrow & \left(b(y). (y \mid \bar{c} \langle \rangle) \right) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c} \langle \rangle)) \mid \bar{b}(c). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \\
 \rightarrow & c(). \left((b(y). (y \mid \bar{c} \langle \rangle)) \mid \bar{b}(c). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c} \langle \rangle \\
 \rightarrow & \mathbf{b}(y). (y \mid \bar{c} \langle \rangle) \mid \bar{\mathbf{b}}(c). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega \\
 \rightarrow & \left(c(). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c} \langle \rangle \\
 \rightarrow & \ast
 \end{aligned}$$

Term Normalization: a Non-linear Example

$$\begin{aligned}
 & \left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c}(\langle \rangle))) \\
 \rightarrow & \left(b(y). (y \mid \bar{c}(\langle \rangle)) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c}(\langle \rangle)) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega) \right) \right) \\
 \rightarrow & c(). \left((b(y). (y \mid \bar{c}(\langle \rangle)) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega) \right) \mid \bar{c}(\langle \rangle) \\
 \rightarrow & b(y). (y \mid \bar{c}(\langle \rangle)) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \\
 \rightarrow & \left(c(). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c}(\langle \rangle) \\
 \rightarrow & \star
 \end{aligned}$$

Term Normalization: a Non-linear Example

$$\begin{aligned}
 & \left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c} \langle \rangle)) \\
 \rightarrow & \quad (b(y). (y \mid \bar{c} \langle \rangle)) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c} \langle \rangle)) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \\
 \rightarrow & \quad c(). \left((b(y). (y \mid \bar{c} \langle \rangle)) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c} \langle \rangle \\
 \rightarrow & \quad b(y). (y \mid \bar{c} \langle \rangle) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \\
 \rightarrow & \quad \left(c(). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \mid \bar{c} \langle \rangle \\
 \rightarrow & \quad \star
 \end{aligned}$$

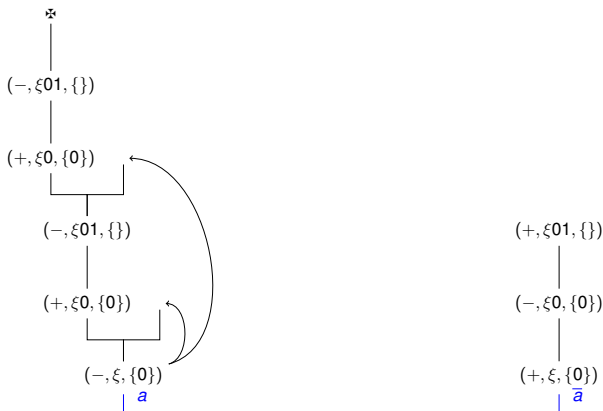
Term Normalization: Ludics style

$$\left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c}(\cdot)))$$



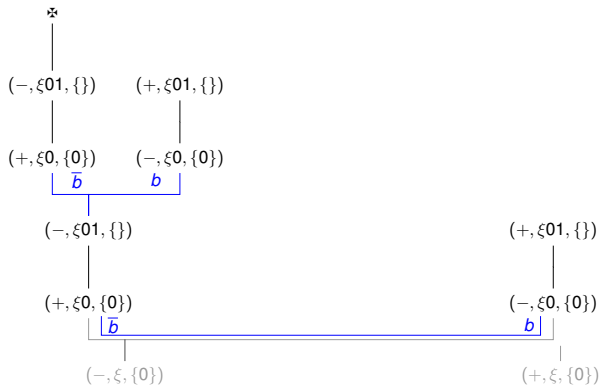
Term Normalization: Ludics style

$$\left(a(x). \left(x \mid \bar{b}(c). \left(x \mid \bar{b}(c). * + \sum_{u \neq c} u(\vec{x}_i). \Omega \right) \right) \right) \mid \bar{a}(b(y). (y \mid \bar{c}(\cdot)))$$



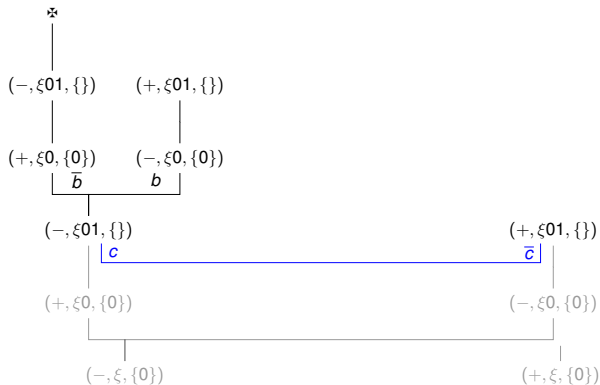
Term Normalization: Ludics style

$$\rightarrow (b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). \left((b(y). (y \mid \bar{c}(\cdot))) \mid \bar{b}(c). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \right)$$



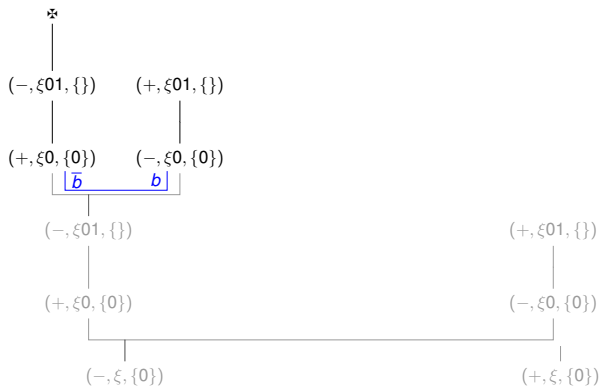
Term Normalization: Ludics style

$$\rightarrow c(). \left((b(y). (y | \bar{c}\langle \rangle)) \mid \bar{b}\langle c(). \star + \sum_{u \neq c} u(\vec{x}_i). \Omega \rangle \right) \mid \bar{c}\langle \rangle$$



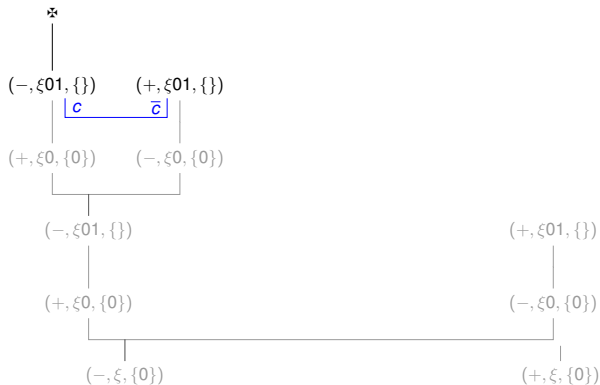
Term Normalization: Ludics style

$$\rightarrow b(y). (y \mid \bar{c}()) \mid \bar{b}(c()). \ast + \sum_{u \neq c} u(\vec{x}_i). \Omega$$



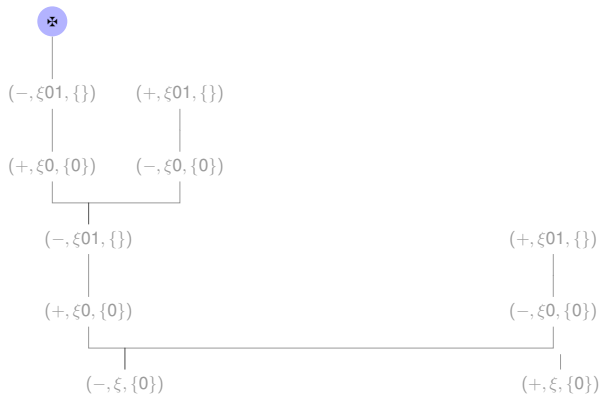
Term Normalization: Ludics style

$$\rightarrow (c().\star + \sum_{u \neq c} u(\vec{x}_i).\Omega) \mid \bar{c}\langle \rangle$$



Term Normalization: Ludics style

→ ✖



Generators

A **design generator** is given as a set of recursive definitions of positive or negative c-designs:

Definition

A design generator G is a triple $(\mathcal{P}, \mathcal{N}, g)$ such that:

- \mathcal{P} and \mathcal{N} are disjoint sets
- $\forall P \in \mathcal{P}$, $g(P)$ is
 - either \exists
 - or Ω
 - or $N_0 \mid \bar{u}\langle N_1, \dots, N_n \rangle$ with $N_i \in \mathcal{N}$
- $\forall N \in \mathcal{N}$, $g(N)$ is
 - either a variable x
 - or $\sum u(\vec{x}_u).P_u$ with $P_u \in \mathcal{P}$

Generators: Reduction

Reduction rule and **normalization** may be defined on generators in the same way as they are on c-designs.

The reduction rule $\sum_u u(x_1 \dots x_{ar(u)}) \cdot P_u | \overline{u_0} \langle N_1 \dots N_{ar(u_0)} \rangle$ is extended by corecursion to c-designs defined by generators.

Generators: Reduction

The procedure is not effective as replacement may be infinite (as a design may contain an infinite number of the same variable).

Instead of the previous reduction, one may define reduction by means of **stack of environments**: substitutions are not explicitly done but kept in the environment.

Generators: an Example

Example

The fax may be generated by $(\{\}, \{N\}, \eta)$ where

$$\eta(N) = \sum u(\vec{x}_u). (N \mid \bar{u}\langle\overline{\eta(x_u)}\rangle)$$

Let P and N without cuts and identities,

- $\llbracket P[\overline{\eta(x_i)}/\vec{x}_i] \rrbracket = P$
- $\llbracket \eta(N[\overline{\eta(x_i)}/\vec{x}_i]) \rrbracket = N$

Standard C-designs and Finite Automata (1)

A **standard** c-design (ie a *Girard's design*) is a c-design that is

- linear, cut-free, identity-free,
- $\neq \Omega$, with a finite set of free variables.

A **deterministic finite automaton** M is a tuple $(\Sigma, Q, \delta, q_0, Q_F)$:

- Σ is an alphabet
- Q is a finite set
- $\delta : Q \times \Sigma \rightarrow Q$ is the transition function,
 $q \xrightarrow{a} q'$ iff $\delta(q, a) = q'$
- $q_0 \in Q$ is the initial state and $Q_F \subset Q$ the set of final states

M **accepts** a word $a_1 \dots a_n$

if $\exists q_i \in Q$ s.t. $q_0 \xrightarrow{a_1} q_1 \xrightarrow{a_2} \dots \xrightarrow{a_n} q_f \in Q_F$

Standard C-designs and Finite Automata (2)

Theorem (Terui)

- Let M be a DFA, there exists a finitely generated positive **standard** c-design P such that M accepts w iff $\llbracket P[w^*/x] \rrbracket = \star$
- and vice-versa.

The proof is based on the following:

- A name nil for the empty string
- For each state q , two c-designs q^+ and q^-
- $g(q_i^+) = x \mid \bar{\uparrow}\langle q_i^- \rangle$
- $g(q_i^-) = \sum_{a \in A} a(x).q_{j_a}^+ + \text{nil}().\star$, if $\forall a \in A, q_i \xrightarrow{a} q_{j_a}$ and $q_i \in Q_F$
- $g(q_i^-) = \sum_{a \in A} a(x).q_{j_a}^+ + \text{nil}().\Omega$, if $\forall a \in A, q_i \xrightarrow{a} q_{j_a}$ and $q_i \notin Q_F$

C-designs and Turing Machines

Theorem (Terui)

- *Let P be a finitely generated positive c -design, there exists a Turing Machine M such that M accepts w iff $\llbracket P[w^*/x] \rrbracket = \star$*
- *Let M be a Turing Machine, there exists a finitely generated positive **identity-free linear** c -design M such that M accepts w iff $\llbracket P[w^*/x] \rrbracket = \star$*

C-designs and Turing Machines

In other words:

- **Girard's finite designs recognize exactly regular languages**
- **Cuts are necessary to recover the full expressive power of Turing machines**

C-designs and Grammars: an Example

Example (Language $a^n b^n, n > 0$)

A string w is encoded as a negative c-design w^* :

- $\epsilon^* = \uparrow (x).x|\overline{\text{nil}}\langle \rangle$
- $(a.w)^* = \uparrow (x).x|\overline{a}\langle w^* \rangle$

Use of a stack to postpone what remains to be done:

- $G[t] = M[\text{nil}().\star, t]$
- $M[z, t] = t \mid \overline{\uparrow}\langle a(x).M'[z, x] \rangle$
- $M'[z, t] = t \mid \overline{\uparrow} \langle$
 $\quad b(x).(x|\overline{\uparrow}\langle z \rangle)$
 $\quad +$
 $\quad a(x).M[b(x).(x|\overline{\uparrow}\langle z \rangle), \uparrow (y).y|\overline{a}\langle x \rangle] \quad \rangle$

C-designs and Grammar

Formalisms used in Natural Language processing may be represented with C-designs.

What do we get? Remember the main objectives of Terui:

- **Monism**: One kind of object versus grammar/sentence, ...
- **Interaction**:
 - Acceptance viewed as orthogonality
 - Symmetry of the process
- **Existentialism**: not necessarily closed objects

Formalization given in Ludics may be rewritten with C-designs:

Example (Beating)

With the question (a) *Have you stopped beating your father?*, one forces the following exchange:

- (e_0) *Did you beat your father ?*
- (e_1) *Yes*
- (e_2) *Have you stopped beating him ?*

Ludics

$$\frac{\frac{\xi.0.1.0 \vdash}{\vdash \xi.0.1} \quad \vdash \xi.0.2}{\xi.0 \vdash} \quad \vdash \xi$$

C-design with presupposition

$$x \mid \bar{e}_0 < e_1.t \mid \bar{e}_2 < y > >$$

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C-design without presupposition

$$x \mid \bar{e}_0 < e_1.t \mid \bar{e}_2 < y > +z >$$

Example (Schopenhauer)

The fourth stratagem (again) If you want to draw a conclusion, you must not let it be foreseen, but you must get the premises admitted one by one, unobserved, mingling them here and there in your talk. [. . .] In this way you conceal your game until you have obtained all the admissions that are necessary, and so reach your goal by making a circuit.

Remember that a formalization of the speaker view point may be done with:

$$\begin{array}{c}
 \downarrow [[\mathcal{D}_\alpha, \mathfrak{F}ax_{\alpha,\xi.1.0}]] \quad \downarrow [[\mathcal{D}_\beta, \mathfrak{F}ax_{\beta,\xi.2.0}]] \\
 \vdots \qquad \qquad \qquad \vdots \\
 \frac{\vdash \xi.1.0}{\xi.1 \vdash} \qquad \qquad \frac{\vdash \xi.2.0}{\xi.2 \vdash} \qquad \qquad \xi.3 \vdash \\
 \hline
 \vdash \xi
 \end{array}$$

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 \hline
 \vdash \xi
 \end{array}$$

It may be rewritten as the following C-design:

$$x \mid \bar{e} < d(t).(Fax_t \mid \bar{a} < x_a >), q(t).(Fax_t \mid \bar{b} < x_b >), z >$$

$$\begin{array}{c}
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Propositions *A* and *B* previously **claimed** are used now as **arguments**.

$$\begin{array}{c}
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Addressee has to locate a free variable. If he still accepts propositions A and B , the only choice is z .

Petitio principii is a right place for using C-designs:
Proposition that has to be proved is already given (implicitly or not) in the premises !

Example

– I would like you to tell where that comes my daughter is dumb.
– There is nothing easier. This comes from what she has lost her speech.

We consider:

- e_1 : Your daughter is dumb
- e_2 : Your daughter has lost her speech

The design \mathcal{I} corresponding to “*Your daughter is dumb because she lost her speech.*”:

$$\mathcal{I} = e_0(x).x \mid \overline{e_1} < \mathcal{N} >$$

- $\overline{e_1}$ is the positive action corresponding to the claim of utterance e_1 : *Your daughter is dumb*
- C-design \mathcal{N} is a (dialog) design for justifying e_1

- Argumentations for e_1 and e_2 are *quite* identical.
- One can take the same c-design for \mathcal{N} and \mathcal{I} :

$$e'_0(y).y \mid \overline{e_2} < \mathcal{I} >$$

Hence the design modeling the second utterance may be an infinite C-design:

$$e_0(x).x \mid \overline{e_1} < e'_0(y).y \mid \overline{e_2} < e_0(z).z \mid \overline{e_1} < e'_0(t).t \mid \overline{e_2} < \dots >>>>$$

Hence there is no place (no usable free variable) to continue the exchange!